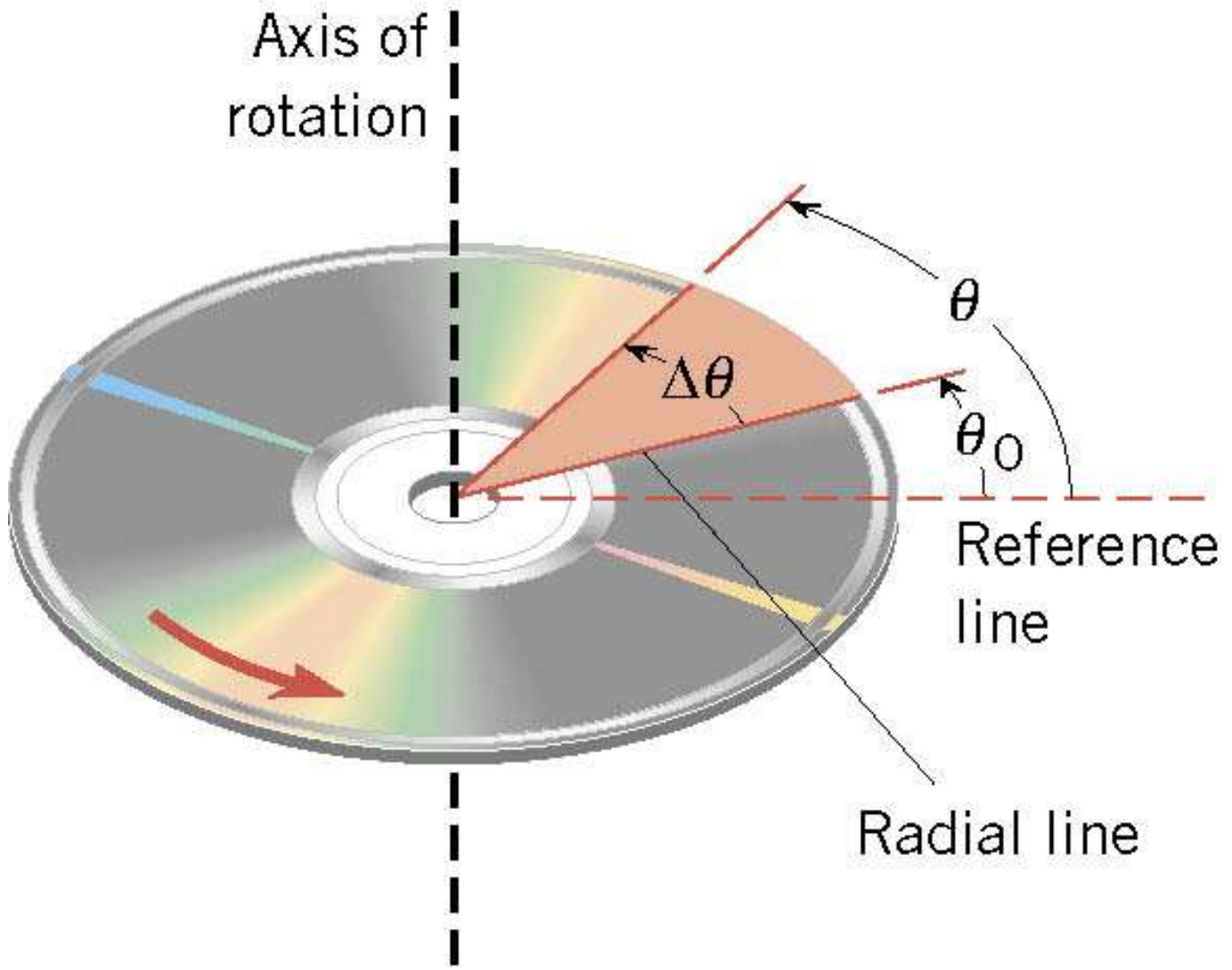
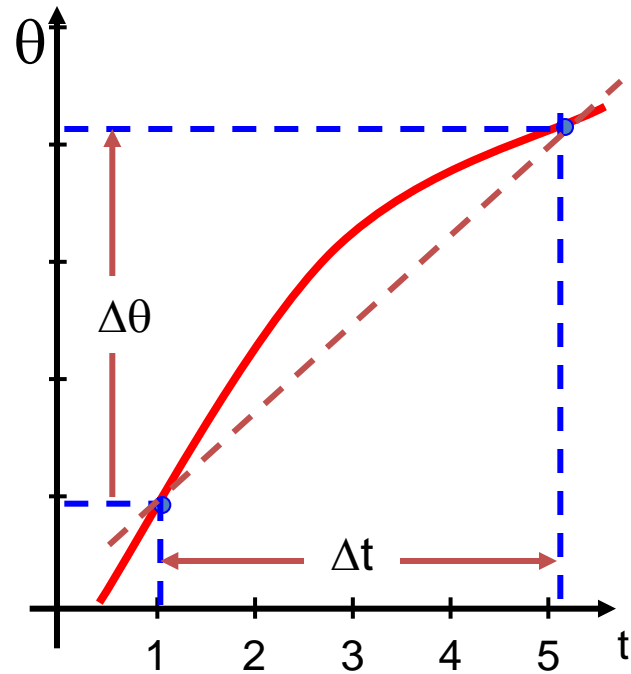
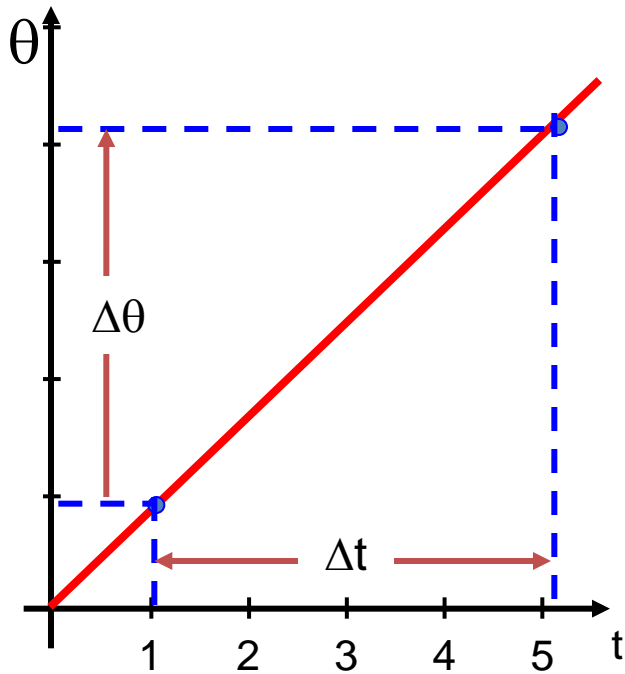


Stationary
skater
or pivot



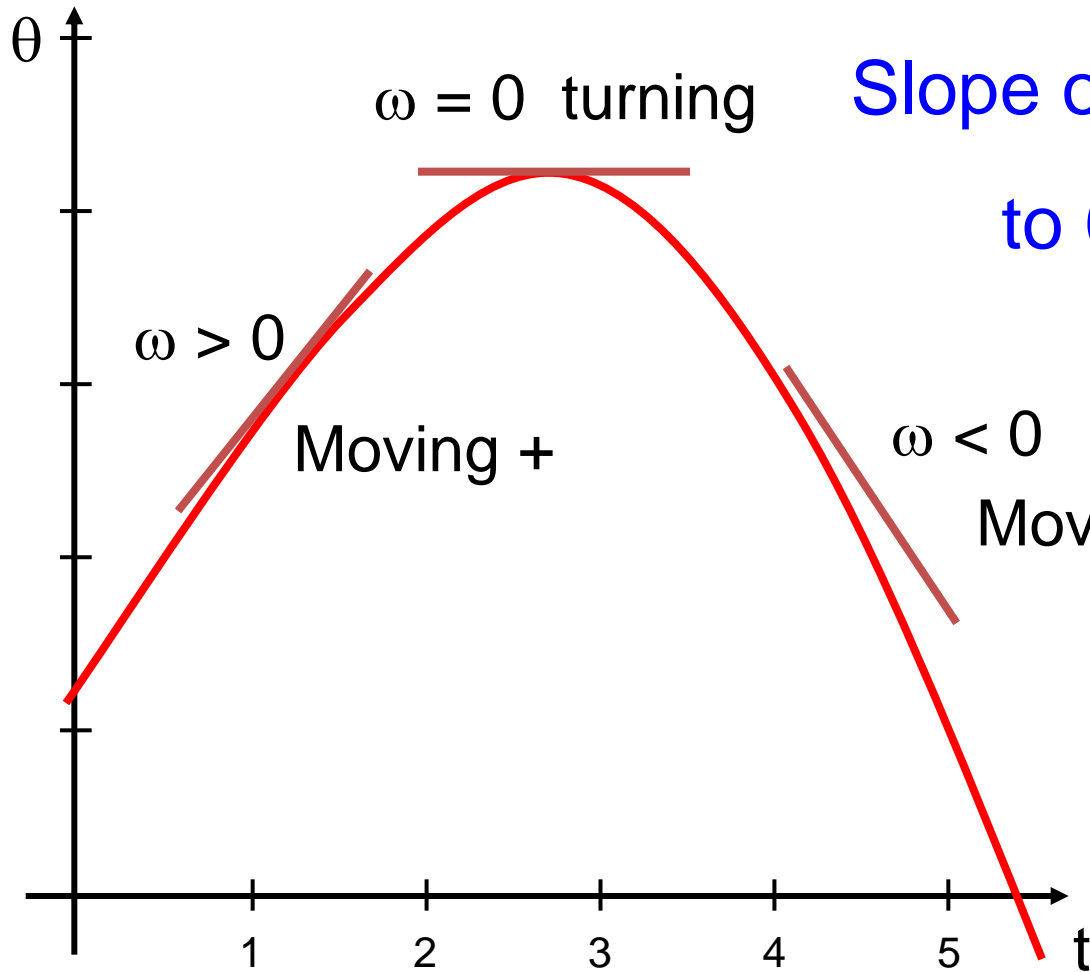
Average Velocity

$$\vec{\omega}_{average} = \frac{\Delta \vec{\theta}}{\Delta t}$$

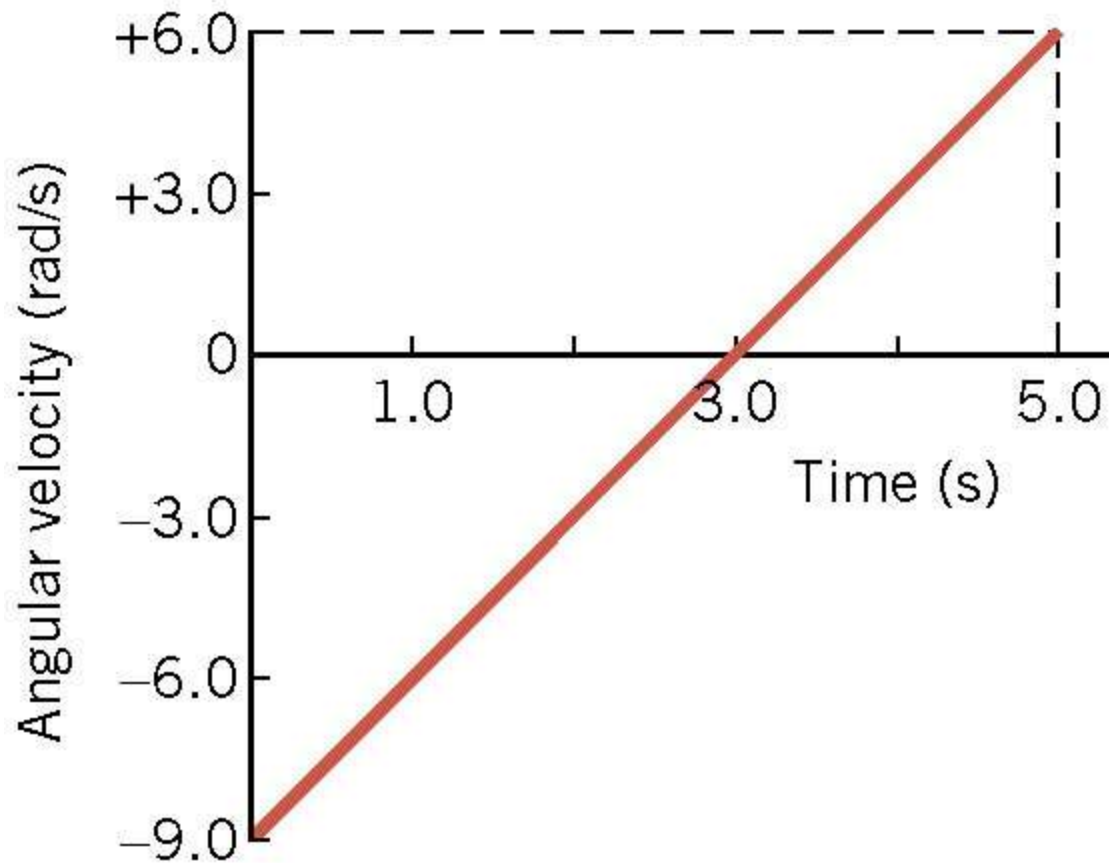


Velocity

$$\vec{\omega} = \lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{\theta}}{\Delta t} = \frac{d\vec{\theta}}{dt}$$



Slope of line tangent
to θ - t graph

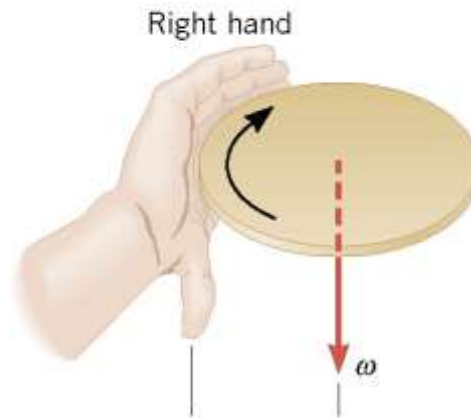
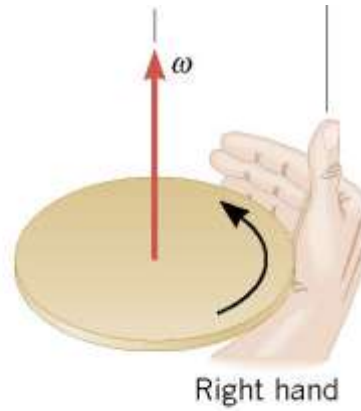


Work with constant α , so ω - t graph is linear. Slope of ω - t graph is α .

$$y = b + mx \Rightarrow \omega_f = \omega_i + \alpha t$$

$$\omega_{ave} = \frac{\omega_f + \omega_i}{2}$$

Vector Direction





(a) Angular speed increasing



(b) Angular speed decreasing

$\vec{\alpha} \uparrow \vec{\omega} \Leftrightarrow$ speeding up

$\vec{\alpha} \downarrow \vec{\omega} \Leftrightarrow$ slowing down



(b) Angular speed decreasing

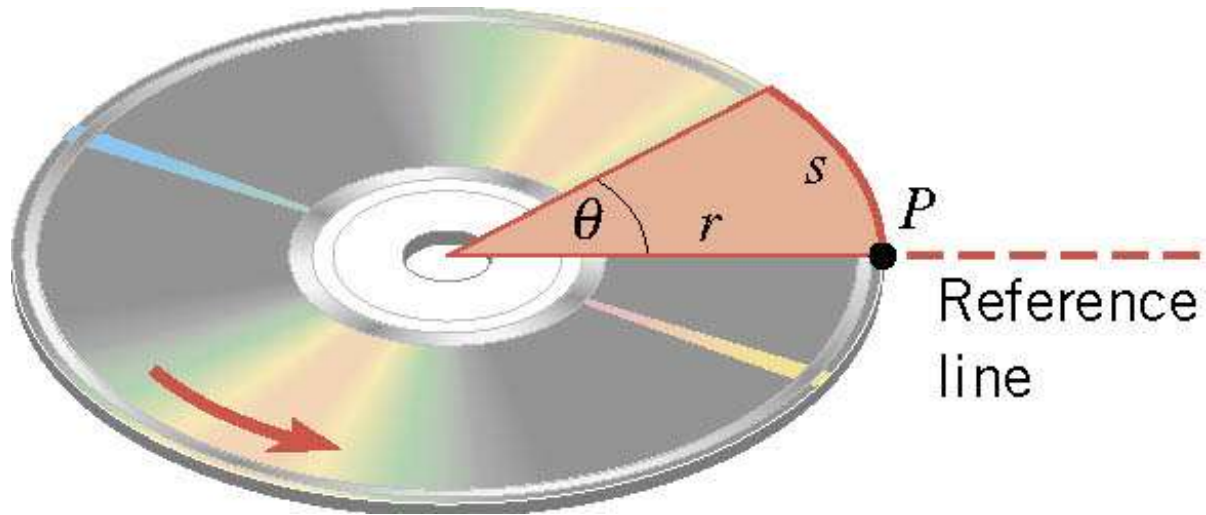


(a) Angular speed increasing

$\vec{\alpha} \uparrow \vec{\omega} \Leftrightarrow$ speeding up

$\vec{\alpha} \downarrow \vec{\omega} \Leftrightarrow$ slowing down

Tangential Variables



$$s = r\theta$$

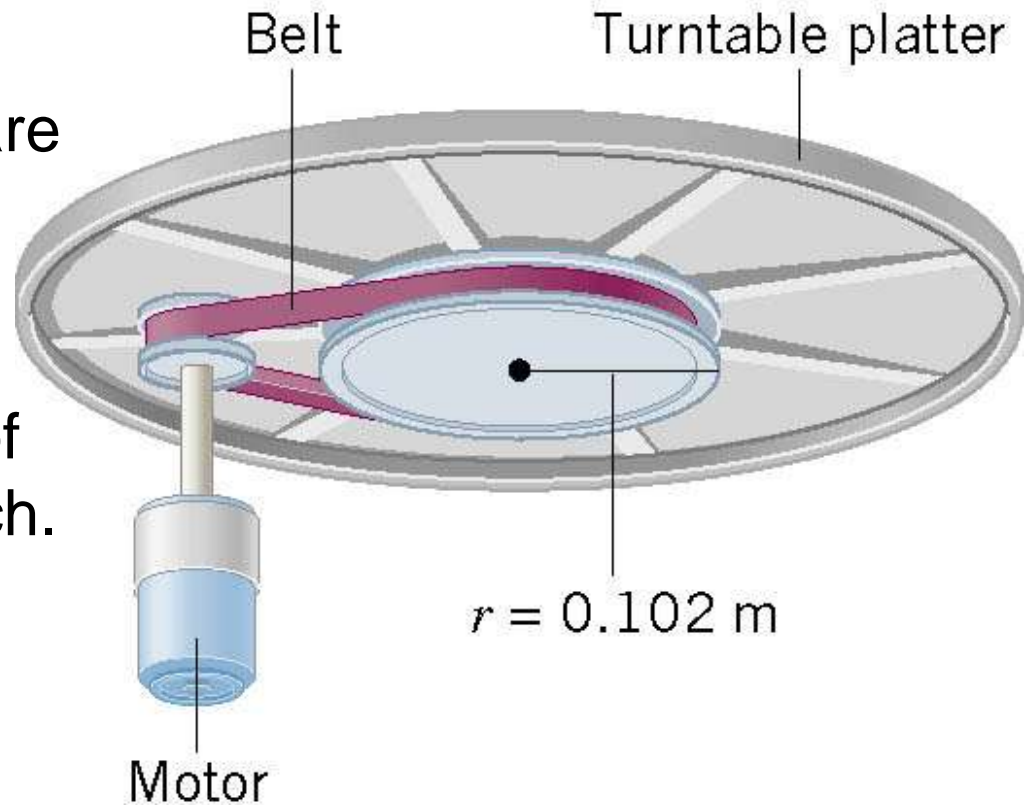
$$\frac{ds}{dt} = r \frac{d\theta}{dt} \Rightarrow v_{tan} = r\omega$$

$$\frac{dv_{tan}}{dt} = r \frac{d\omega}{dt} \Rightarrow a_{tan} = r\alpha$$

Belts

Small disk and big disk are connected by belt.

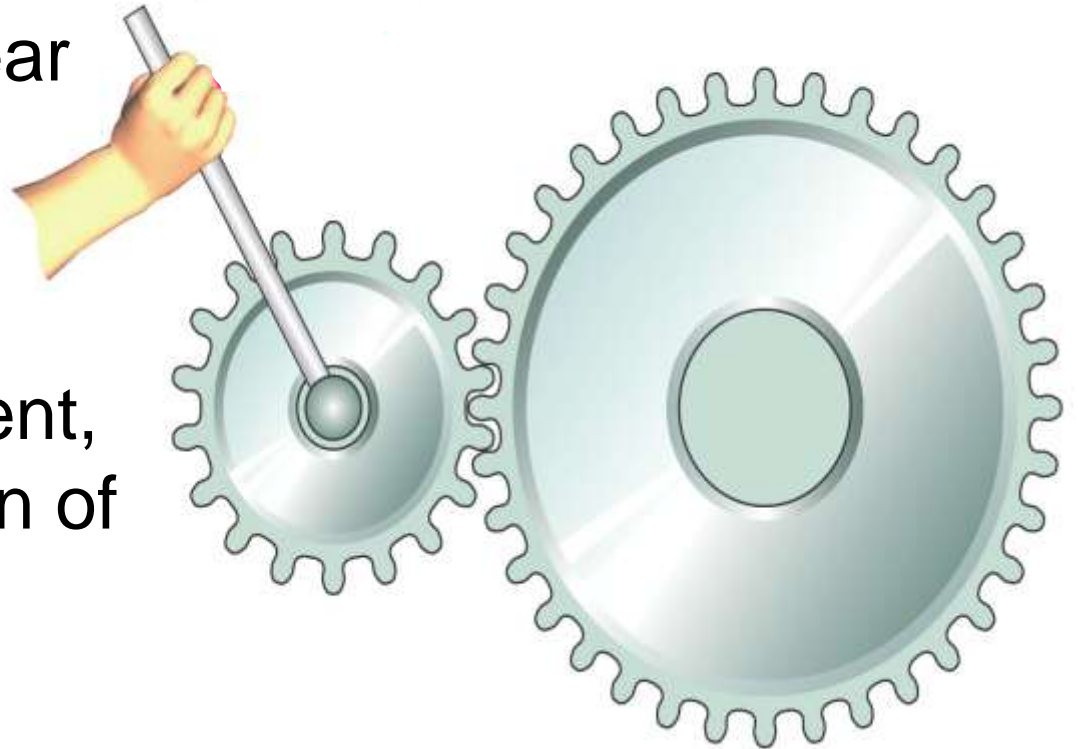
Tangential displacement, velocity, & acceleration of disks and belt must match.



Geared Wheels

Small gear and big gear are touching and cannot slip.

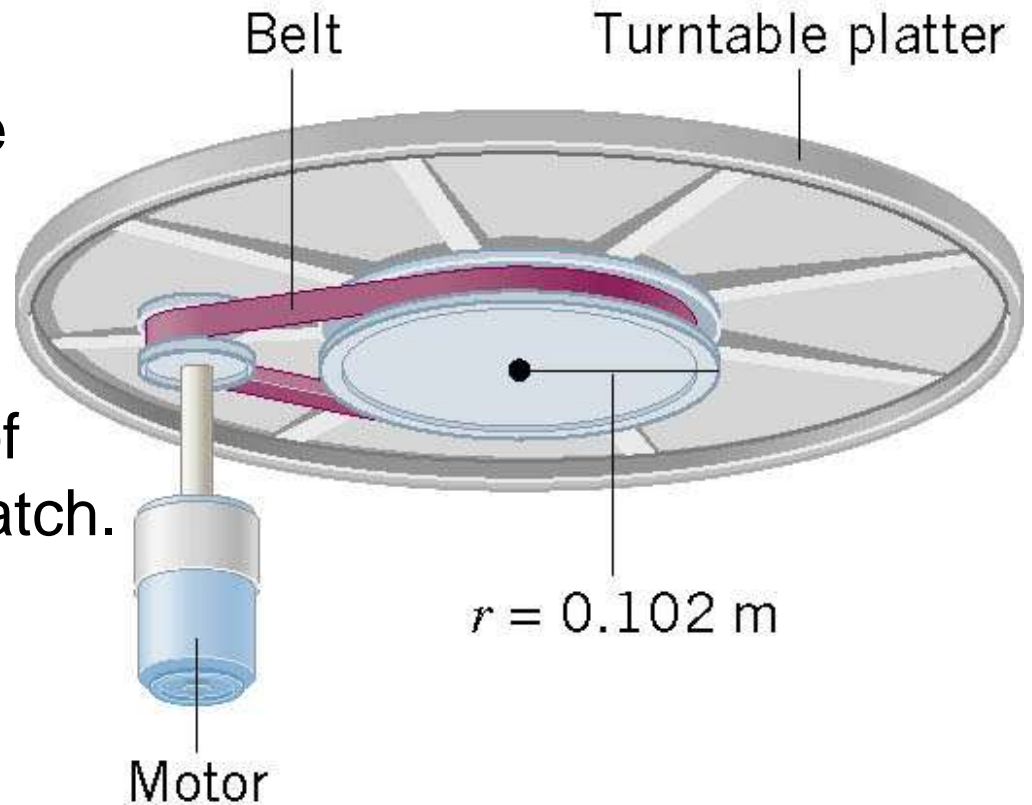
Tangential displacement, velocity, & acceleration of gears must match.



Common Axles

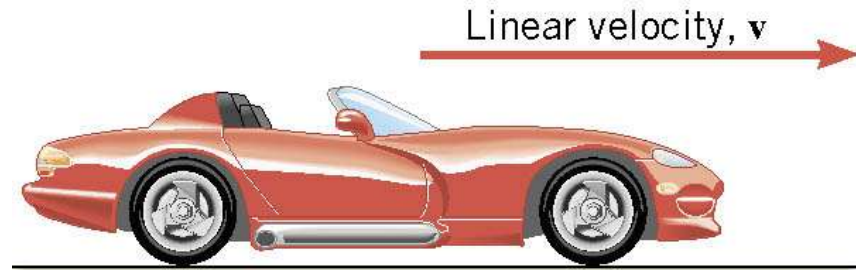
Small disk and motor are connected by an axle.

Rotational displacement, velocity, & acceleration of disks and motor must match.

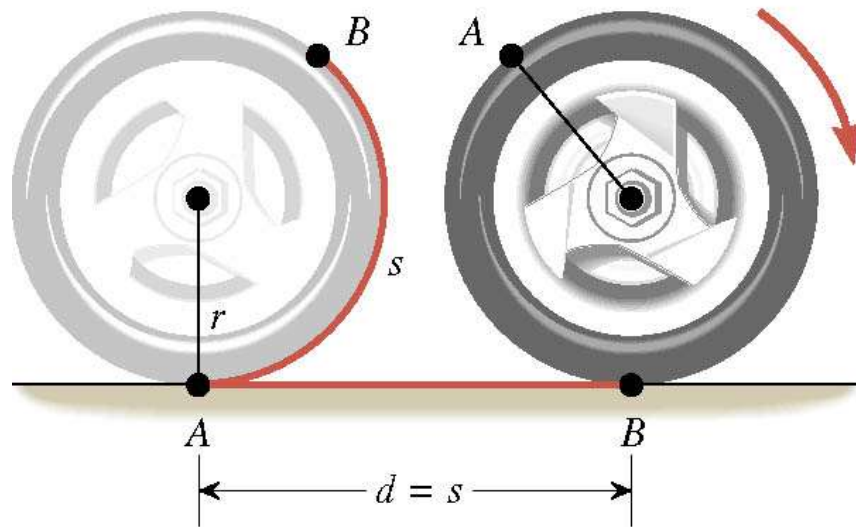


Rolling

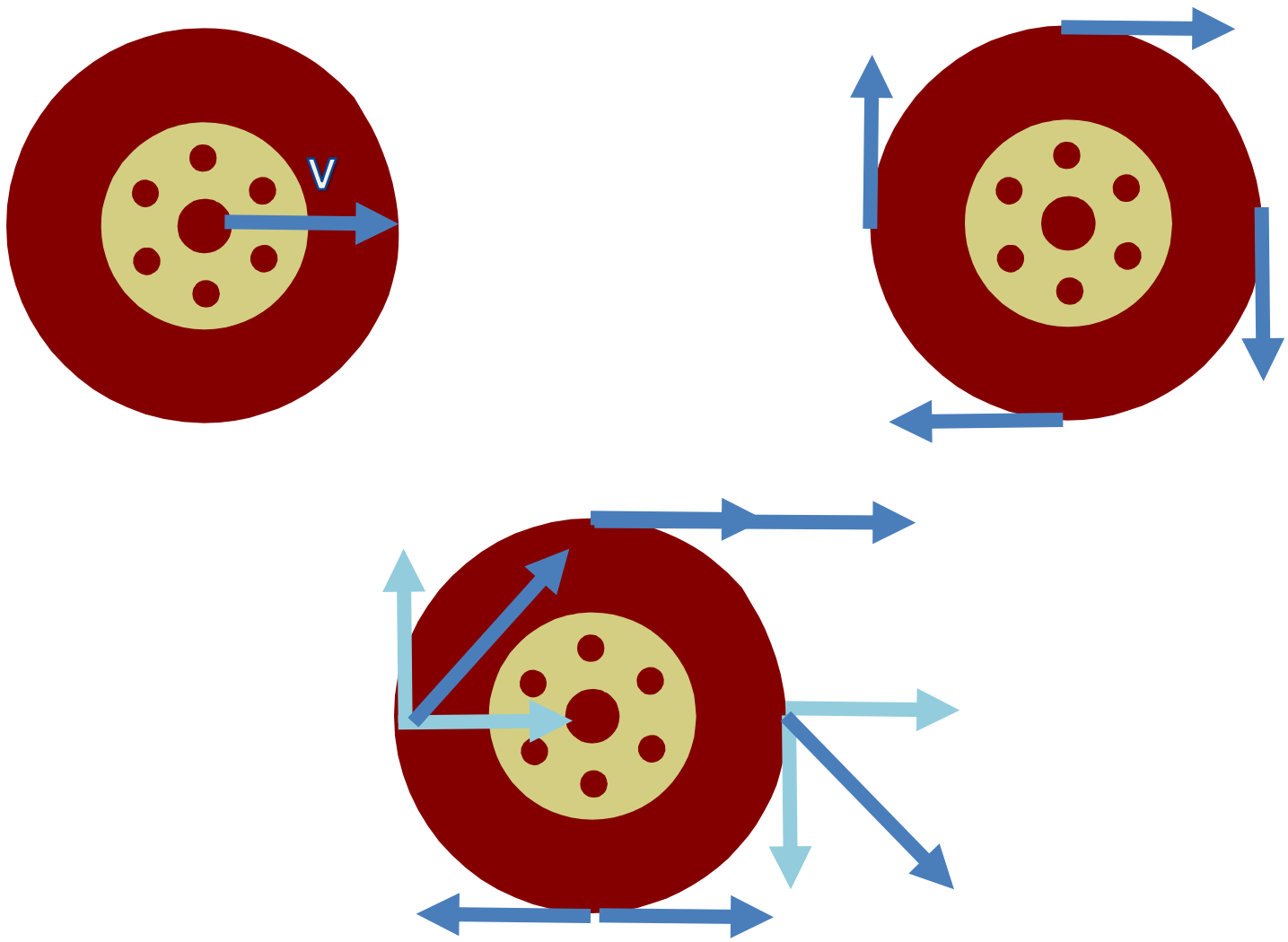
If wheel does not slip, tangential displacement, velocity, & acceleration must match linear displacement, velocity, & acceleration.



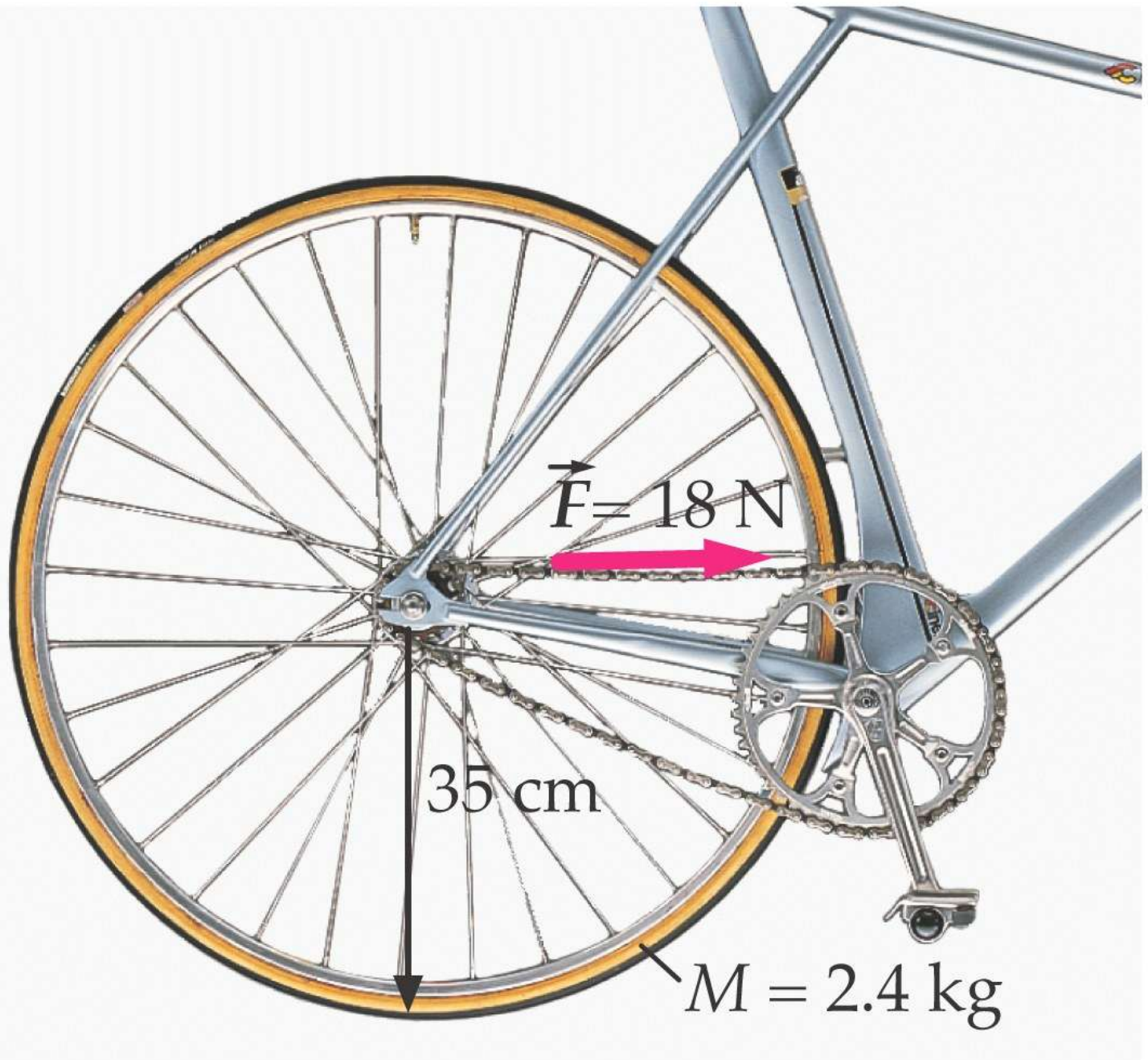
(a)

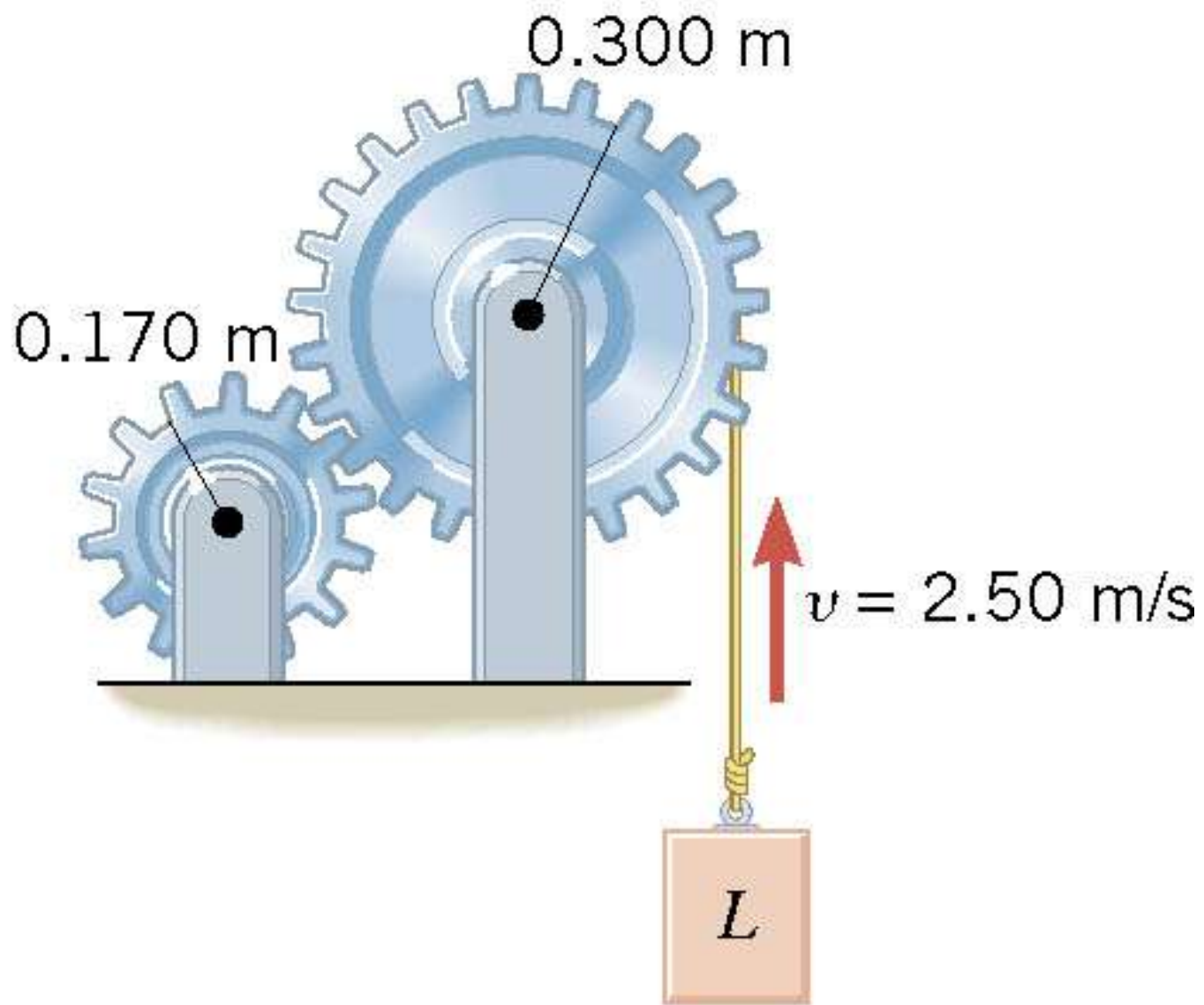


(b)



Point of contact is at “rest”





0.100 m diameter

